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# 3.3-V PHASE-LOCK LOOP CLOCK DRIVER WITH POWER DOWN MODE

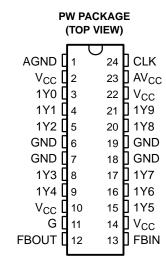
#### **FEATURES**

- **Designed to Meet and Exceed PC133 SDRAM Registered DIMM Specification**
- **Spread Spectrum Clock Compatible**
- Operating Frequency 20 MHz to 175 MHz
- Static Phase Error Distribution at 66 MHz to 166 MHz is ±125 ps
- Jitter (cyc-cyc) at 66 MHz to 166 MHz is |70| ps
- **Advanced Deep Submicron Process Results** in More Than 40% Lower Power Consumption vs Current Generation **PC133 Devices**
- Auto Frequency Detection to Disable **Device (Power-Down Mode)**
- **Available in Plastic 24-Pin TSSOP**
- Distributes One Clock Input to One Bank of 10 Outputs
- External Feedback (FBIN) Terminal is **Used to Synchronize the Outputs to the Clock** Input
- 25- $\Omega$  On-Chip Series Damping Resistors
- No External RC Network Required
- Operates at 3.3 V

# **DESCRIPTION**

#### **APPLICATIONS**

- **DRAM Applications**
- **PLL Based Clock Distributors**
- Non-PLL Clock Buffer



The CDCVF2510A is a high-performance, low-skew, low-jitter, phase-lock loop (PLL) clock driver. The CDCVF2510A uses a phase-lock loop (PLL) to precisely align, in both frequency and phase, the feedback (FBOUT) output to the clock (CLK) input signal. It is specifically designed for use with synchronous DRAMs. The CDCVF2510A operates at a 3.3-V  $V_{CC}$  and also provides integrated series-damping resistors that make it ideal for driving point-to-point loads.

One bank of 10 outputs provides 10 low-skew, low-jitter copies of CLK. Output signal duty cycles are adjusted to 50%, independent of the duty cycle at CLK. Outputs are enabled or disabled via the control (G) input. When the G input is high, the outputs switch in phase and frequency with CLK; when the G input is low, the outputs are disabled to the logic-low state. The device automically goes into power-down mode when no input signal (< 1 MHz) is applied to CLK; the outputs go into a low state.

Unlike many products containing PLLs, the CDCVF2510A does not require external RC networks. The loop filter for the PLL is included on-chip, minimizing component count, board space, and cost.

Because it is based on PLL circuitry, the CDCVF2510A requires a stabilization time to achieve phase lock of the feedback signal to the reference signal. This stabilization time is required following power up and application of a fixed-frequency, a fixed-phase signal at CLK, or following any changes to the PLL reference or feedback signals. The PLL can be bypassed by strapping AV<sub>CC</sub> to ground to use as a simple clock buffer.



Please be aware that an important notice concerning availability, standard warranty, and use in critical applications of Texas Instruments semiconductor products and disclaimers thereto appears at the end of this data sheet.



The CDCVF2510A is characterized for operation from 0°C to 85°C.

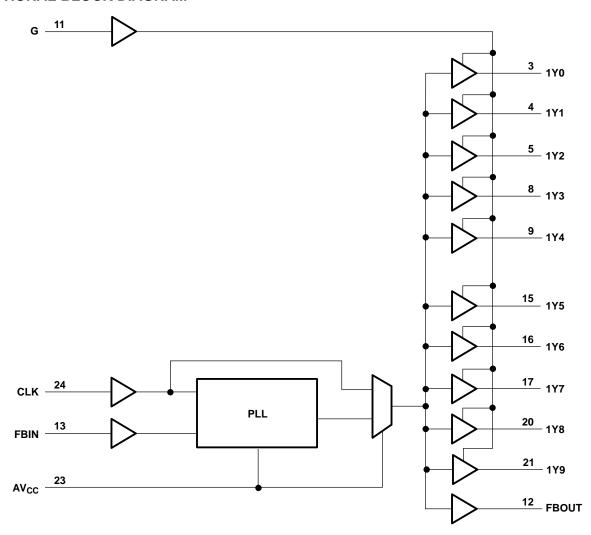
For application information see the application reports *High Speed Distribution Design Techniques for CDC509/516/2509/2510/2516* (literature number SLMA003) and *Using CDC2509A/2510A PLL With Spread Spectrum Clocking (SSC)* (literature number SCAA039).

#### **FUNCTION TABLE**

INPUTS			OUT	PLL	
AVDD	G	CLK	1Y(0:9)	FBOUT	
GND	Н	L	L	L	Bypassed / Off
GND	Н	Н	Н	Н	Bypassed / Off
GND	L	L	L	L	Bypassed / Off
GND	L	Н	L	Н	Bypassed / Off
GND	L	Toggling	L	Toggling in phase to CLK	Bypassed / Off
3.3 V (nom)	L	Н	L	L	On
3.3 V (nom)	L	Toggling	L	Toggling in phase to CLK	On
3.3 V (nom)	Н	L	L	L	On
3.3 V (nom)	Н	Н	Н	Н	On
3.3 V (nom)	Н	Toggling	Toggling in phase to CLK	Toggling in phase to CLK	On
3.3 V (nom)	Х	< 1 MHz	L	L	Off



# **FUNCTIONAL BLOCK DIAGRAM**



## **AVAILABLE OPTIONS**

т.	PACKAGE
'A	SMALL OUTLINE (PW)
0°C to 05°C	CDCVF2510APWR
0°C to 85°C	CDCVF2510APW



#### **Terminal Functions**

TE	TERMINAL		TERMINAL		DESCRIPTION
NAME	NO.	ITFE	DESCRIPTION		
CLK	24	-	Clock input. CLK provides the clock signal to be distributed by the CDCVF2510A clock driver. CLK is used to provide the reference signal to the integrated PLL that generates the clock output signals. CLK must have a fixed frequency and fixed phase for the PLL to obtain phase lock. Once the circuit is powered up and a valid CLK signal is applied, a stabilization time is required for the PLL to phase lock the feedback signal to its reference signal.		
FBIN	13	I	Feedback input. FBIN provides the feedback signal to the internal PLL. FBIN must be hard-wired to FBOUT to complete the PLL. The integrated PLL synchronizes CLK and FBIN so that there is nominally zero phase error between CLK and FBIN.		
G	11	I	Output bank enable. G is the output enable for outputs 1Y(0:9). When G is low, outputs 1Y(0:9) are disabled to a logic-low state. When G is high, all outputs 1Y(0:9) are enabled and switch at the same frequency as CLK.		
FBOUT	12	0	Feedback output. FBOUT is dedicated for external feedback. It switches at the same frequency as CLK. When externally wired to FBIN, FBOUT completes the feedback loop of the PLL. FBOUT has an integrated $25-\Omega$ series-damping resistor.		
1Y (0:9)	3, 4, 5, 8, 9, 15, 16, 17, 20, 21	0	Clock outputs. These outputs provide low-skew copies of CLK. Output bank 1Y(0:9) is enabled via the G input. These outputs can be disabled to a logic-low state by deasserting the G control input. Each output has an integrated $25-\Omega$ series-damping resistor.		
AV <sub>CC</sub>	23	Power	Analog power supply. $AV_{CC}$ provides the power reference for the analog circuitry. In addition, $AV_{CC}$ can be used to bypass the PLL. When $AV_{CC}$ is strapped to ground, PLL is bypassed and CLK is buffered directly to the device outputs.		
AGND	1	Ground	Analog ground. AGND provides the ground reference for the analog circuitry.		
V <sub>CC</sub>	2, 10, 14, 22	Power	Power supply		
GND	6, 7, 18, 19	Ground	Ground		

## **ABSOLUTE MAXIMUM RATINGS**

over operating free-air temperature range (unless otherwise noted)

$AV_{CC}$	Supply voltage range (1)	$AV_{CC} < V_{CC} + 0.7 V$
$V_{CC}$	Supply voltage range	-0.5 V to 4.3 V
$V_{I}$	Input voltage range (2)	-0.5 V to 4.6 V
Vo	Voltage range applied to any output in the high or low state (2)(3)	-0.5 V to V <sub>CC</sub> + 0.5 V
I <sub>IK</sub>	Input clamp current, (V <sub>I</sub> < 0)	–50 mA
I <sub>OK</sub>	Output clamp current, $(V_O < 0 \text{ or } V_O > V_{CC})$	±50 mA
Io	Continuous output current, (V <sub>O</sub> = 0 to V <sub>CC</sub> )	±50 mA
	Continuous current through each V <sub>CC</sub> or GND	±100 mA
$Z_{\Theta JA}$	Junction-to-ambient package thermal impedance (4)	114.5°C/W
$Z_{\Theta JC}$	Junction-to-case thermal impedance (4)	25.7°C/W
TJ	Maximum allowable junction temperature	125°C
T <sub>stg</sub>	Storage temperature range	-65°C to 150°C

- (1) AV<sub>CC</sub> must not exceed V<sub>CC</sub> + 0.7 V.
   (2) The input and output negative-voltage ratings may be exceeded if the input and output clamp-current ratings are observed.
   (3) This value is limited to 4.6 V maximum.
- The package thermal impedance and junction-to-case thermal impedance are calculated in accordance with JESD51 (no air flow condition) and JEDEC252P (high-k board).



# **RECOMMENDED OPERATING CONDITIONS**(1)

		MIN	MAX	UNIT
V <sub>CC</sub> , AV <sub>CC</sub>	Supply voltage	3	3.6	V
$V_{IH}$	High-level input voltage	2		V
$V_{IL}$	Low-level input voltage		0.8	V
$V_{I}$	Input voltage	0	$V_{CC}$	V
I <sub>OH</sub>	High-level output current		-12	mA
I <sub>OL</sub>	Low-level output current,		12	mA
f <sub>clk</sub>	Clock frequency <sup>(2)</sup>	20	175	MHz
	Input clock duty cycle	40%	60%	
	Stabilization time		1	ms

(1) Unused inputs must be held high or low to prevent them from floating.

## **ELECTRICAL CHARACTERISTICS**

over recommended operating free-air temperature range (unless otherwise noted)

	PARAMETER	TEST CONDITIONS	V <sub>CC</sub> , AV <sub>CC</sub>	MIN	TYP <sup>(1)</sup>	MAX	UNIT
$V_{IK}$	Input clamp voltage	I <sub>I</sub> = -18 mA	3 V			-1.2	V
		I <sub>OH</sub> = -100 μA	MIN to MAX	V <sub>CC</sub> -0.2			
$V_{OH}$	High-level output voltage	I <sub>OH</sub> = -12 mA	3 V	2.1			V
		$I_{OH} = -6 \text{ mA}$	3 V	2.4			
		$I_{OL} = 100 \mu A$	MIN to MAX			0.2	
$V_{OL}$	Low-level output voltage	I <sub>OL</sub> = 12 mA	3 V			0.8	V
		I <sub>OL</sub> = 6 mA	3 V			0.55	
		V <sub>O</sub> = 1 V	3 V	-28			
$I_{OH}$	High-level output current	V <sub>O</sub> = 1.65 V	3.3 V		-36		mA
		V <sub>O</sub> = 3.135 V	3.6 V			-8	
		V <sub>O</sub> = 1.95 V	3 V	30			
$I_{OL}$	Low-level output current	V <sub>O</sub> = 1.65 V	3.3 V		40		mA
		V <sub>O</sub> = 0.4 V	3.6 V			10	
I <sub>I</sub>	Input current	V <sub>I</sub> = V <sub>CC</sub> or GND	3.6 V			±5	μΑ
I <sub>CC</sub> <sup>(2)</sup>	Supply current (static, output not switching)	$V_I = V_{CC}$ or GND, $I_O = 0$ , Outputs: low or high	3.6 V, 0 V			40	μΑ
Δl <sub>CC</sub>	Change in supply current	One input at V <sub>CC</sub> - 0.6 V, Other inputs at V <sub>CC</sub> or GND	3.3 V to 3.6 V			500	μΑ
C <sub>i</sub>	Input capacitance	$V_I = V_{CC}$ or GND	3.3 V		2.5		pF
Co	Output capacitance	$V_O = V_{CC}$ or GND	3.3 V		2.8		pF

<sup>(1)</sup> For conditions shown as MIN or MAX, use the appropriate value specified under recommended operating conditions.

<sup>(2)</sup> Time required for the integrated PLL circuit to obtain phase lock of its feedback signal to its reference signal. For phase lock to be obtained, a fixed-frequency, fixed-phase reference signal must be present at CLK. Until phase lock is obtained, the specifications for propagation delay, skew, and jitter parameters given in the switching characteristics table are not applicable. This parameter does not apply for input modulation under SSC application.

<sup>(2)</sup> For dynamic I<sub>CC</sub> vs Frequency, see Figure 9 and Figure 10.



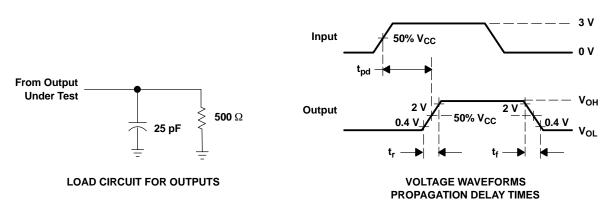
## SWITCHING CHARACTERISTICS

over recommended ranges of supply voltage and operating free-air temperature,  $C_L = 25 \text{ pF}$  (see Note  $^{(1)}$  and Figure 1 and Figure 2)(2)

	PARAMETER	PARAMETER FROM		V <sub>CC</sub> , A	UNIT		
		(INPUT)	(OUTPUT)	MIN	TYP	MAX	
	Phase error time-static (normalized)	CLK↑ = 25 MHz to 65 MHz		-150		150	
t <sub>(φ)</sub>	(see Figure 4 through Figure 7)	CLK↑ = 66 MHz to 175 MHz	FBIN↑	-125		125	ps
t <sub>sk(o)</sub>	Output skew time (3)	Any Y	Any Y			100	ps
	Phase error time-jitter (4)	CLK = 66 MHz to 175 MHz	Any Y or FBOUT	-50		50	ps
		CLK = 25 MHz to 40 MHz				500	
	Jitter <sub>(cycle-cycle)</sub> (see Figure 8)	CLK = 41 MHz to 59 MHz Any Y or FBOUT				200	ps
		CLK = 60 MHz to 175 MHz			65	125	ı
		CLK↑ = 25 MHz to 65 MHz				1.5	
$t_{d(\phi)}$	Dynamic phase offset <sup>(5)</sup>	CLK↑ = 66 MHz to 175 MHz	FBIN↑			0.4	ns
	Duty cycle	f <sub>(CLK)</sub> > 60 MHz	Any Y or FBOUT	45%		55%	
t <sub>r</sub>	Rise time	V <sub>O</sub> = 0.4 V to 2 V	Any Y or FBOUT	0.3		1.1	ns/V
t <sub>f</sub>	Fall time	V <sub>O</sub> = 2 V to 0.4 V	Any Y or FBOUT	0.3		1.1	ns/V
t <sub>PLH</sub>	Low-to-high propagation delay time, bypass mode	CLK	Any Y or FBOUT	1.8		3.9	ns
t <sub>PHL</sub>	High-to-low propagation delay time, bypass mode	CLK	Any Y or FBOUT	1.8		3.9	ns

- The specifications for parameters in this table are applicable only after any appropriate stabilization time has elapsed.
- These parameters are not production tested.
- (3)
- The  $t_{sk(o)}$  specification is only valid for equal loading of all outputs. Calculated per PC DRAM SPEC ( $t_{phase\ error}$ , static jitter( $c_{ycle-to-cycle}$ ). The parameter is assured by design but cannot be 100% production tested.

#### PARAMETER MEASUREMENT INFORMATION



NOTES: A. C<sub>L</sub> includes probe and jig capacitance.

- B. All input pulses are supplied by generators having the following characteristics: PRR  $\leq$  133 MHz,  $Z_O = 50~\Omega$ ,  $t_f \leq$  1.2 ns,  $t_f \leq$  1.2 ns.
- C. The outputs are measured one at a time with one transition per measurement.

Figure 1. Load Circuit and Voltage Waveforms



# PARAMETER MEASUREMENT INFORMATION (continued)

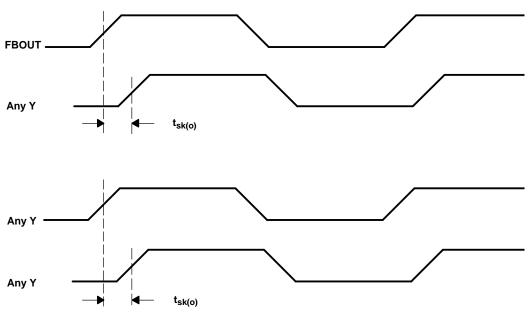
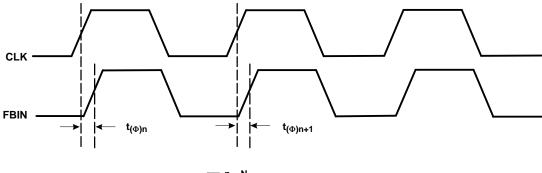


Figure 2. Skew Calculations

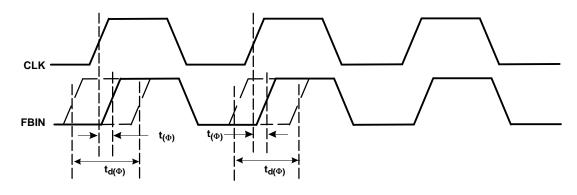


# PARAMETER MEASUREMENT INFORMATION (continued)



$$t_{(\Phi)} = \begin{array}{c} \sum_{1}^{n = N} t_{(\Phi)n} \\ \hline N \end{array} \hspace{0.5cm} \text{(N is a large number of samples)}$$

### a) Static Phase Offset

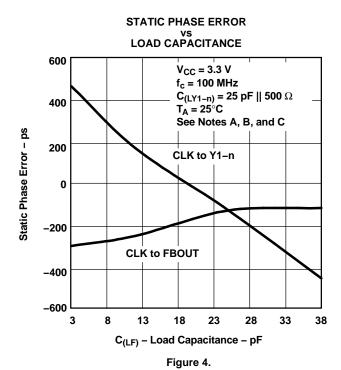


b) Dynamic Phase Offset

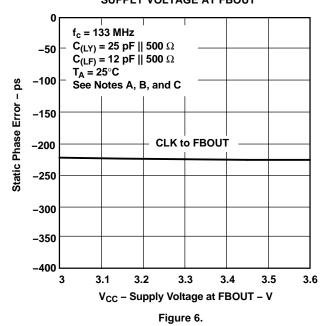
Figure 3. Static and Dynmaic Phase Offset



#### TYPICAL CHARACTERISTICS



# STATIC PHASE ERROR VS SUPPLY VOLTAGE AT FBOUT



- A. Trace length FBOUT to FBIN = 5 mm,  $Z_O = 50\Omega$
- B.  $C_{(LY)}$  = Lumped capacitive load  $Y_{1-n}$
- C.  $C_{(LFx)}$  = Lumped feedback capacitance at FBOUT = FBIN

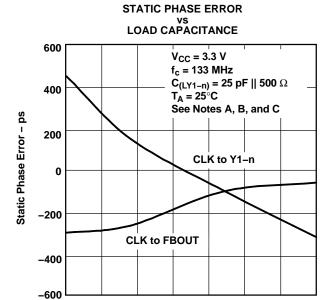


Figure 5.

C<sub>(LF)</sub> - Load Capacitance - pF

18

23

28

33

38

3

8

13

#### STATIC PHASE ERROR VS CLOCK FREQUENCY

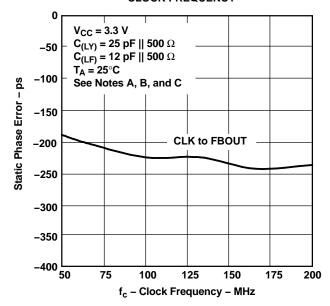


Figure 7.



# TYPICAL CHARACTERISTICS (continued)

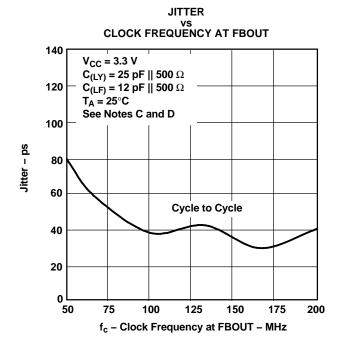
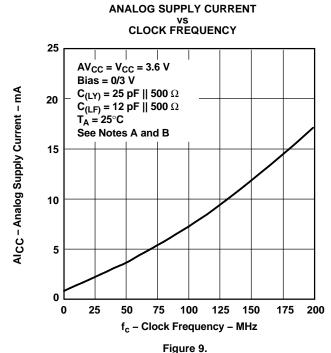
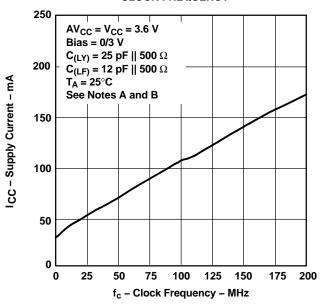


Figure 8.



SUPPLY CURRENT vs CLOCK FREQUENCY



- Figure 10.
- A. Trace length FBOUT to FBIN = 5 mm,  $Z_0$  =  $50\Omega$
- B.  $C_{(LY)}$  = Lumped capacitive load  $Y_{1-n}$
- C.  $C_{(LFx)}$  = Lumped feedback capacitance at FBOUT = FBIN
- D. C<sub>(LFx)</sub> = Lumped feedback capacitance at FBOUT = FBIN



# **Revision History**

# **Table 1. Revision History**

Date	Rev	Page	Section	Description
04/11/05	В	6	Switching Characteristics	Added static phase error - 25 MHz to 65 MHz
				Added jitter - 25 MHz to 65 MHz
				Added Dynamic Phase Offset specification
		7	Figure 2	Revised into two figures
		-	Figure 3	Added Figure 3 for a diagram of dynamic phase offset



## TAPE AND REEL INFORMATION





A0	Dimension designed to accommodate the component width
B0	Dimension designed to accommodate the component length
K0	Dimension designed to accommodate the component thickness
W	Overall width of the carrier tape
P1	Pitch between successive cavity centers

# QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE



#### \*All dimensions are nominal

Device		Package Drawing			Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
CDCVF2510APWR	TSSOP	PW	24	2000	330.0	16.4	6.95	8.3	1.6	8.0	16.0	Q1





#### \*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
CDCVF2510APWR	TSSOP	PW	24	2000	346.0	346.0	33.0

# PW (R-PDSO-G\*\*)

#### 14 PINS SHOWN

# PLASTIC SMALL-OUTLINE PACKAGE



NOTES: A. All linear dimensions are in millimeters.

B. This drawing is subject to change without notice.

C. Body dimensions do not include mold flash or protrusion not to exceed 0,15.

D. Falls within JEDEC MO-153

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